

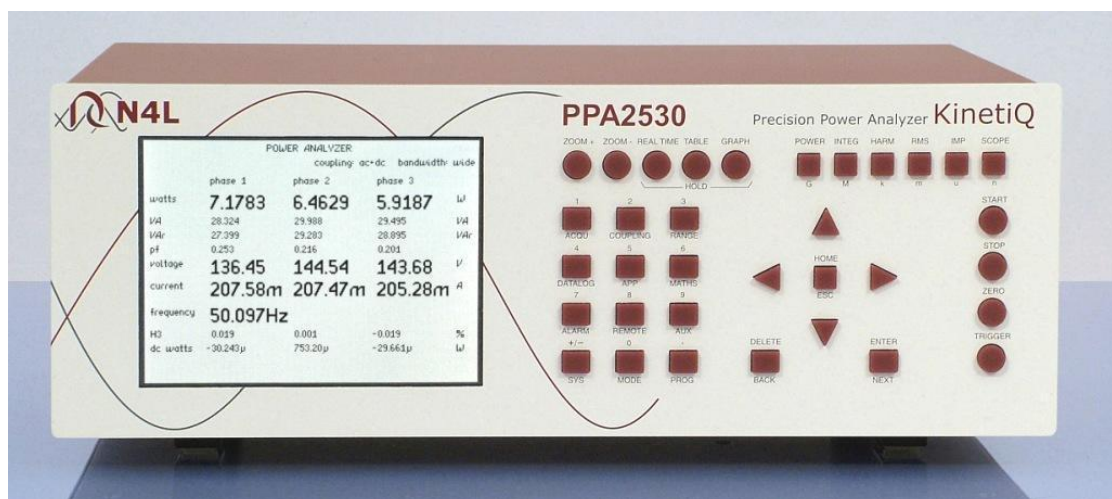


N4L Newtons4th Ltd

PPA2500 PPA2600

KinetiQ

Communications manual



Firmware v1.100

10th April 2017

IMPORTANT SAFETY INSTRUCTIONS

This equipment is designed to comply with BSEN 61010-1 (2001) (Safety requirements for electrical equipment for measurement, control, and laboratory use) – observe the following precautions:

- Ensure that the supply voltage agrees with the rating of the instrument printed on the back panel **before** connecting the mains cord to the supply.
- This appliance **must** be earthed. Ensure that the instrument is powered from a properly grounded supply.
- The inputs are rated at 1kV rms or dc cat II; 600V rms or dc cat III. **Do not exceed the rated input.**
- Keep the ventilation holes on the underneath and rear free from obstruction.
- Do not operate or store under conditions where condensation may occur or where conducting debris may enter the case.
- There are no user serviceable parts inside the instrument – do not attempt to open the instrument, refer service to the manufacturer or his appointed agent.

Note: Newtons4th Ltd. shall not be liable for any consequential damages, losses, costs or expenses arising from the use or misuse of this product however caused.

ABOUT THIS MANUAL

This manual gives details of the communication commands recognized by the PSM25/26xx series of instruments over RS232, USB, LAN or GPIB. For more general operating instructions for the instrument refer to the specific user manual.

Each command is listed alphabetically with details of any arguments and reply. A one line summary of each command is given in the appendix. Although most of the commands apply to all instruments in the range there are some commands that are specific to one instrument or another.

The information in this manual is believed to be accurate and complete but Newtons4th Ltd cannot accept any liability whatsoever for any consequential damage or losses arising from any errors, inaccuracies, or omissions.

Revision 1.100

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1 Using remote control

The instrument is fitted with an RS232 serial communications port and USB interface as standard, and may have an IEEE488 (GPIB) interface or LAN interface fitted as an option. All the interfaces use the same ASCII protocol with the exception of the end of line terminators:

	Rx expects	Tx sends
RS232 USB, LAN	carriage return (line feed ignored)	carriage return and line feed
IEEE488	carriage return or line feed or EOI	carriage return with EOI

All the functions of the instrument can be programmed via any interface, and results read back. When the IEEE488 interface is set to 'remote' the other ports are ignored.

The commands are not case sensitive and white space characters are ignored (e.g. tabs and spaces). Replies from the instrument are always upper case, delimited by commas, without spaces.

Only the first six characters of any command are important – any further characters will be ignored. For example, the command to set the generator frequency is FREQUE but the full word FREQUENCY may be sent as the redundant NCY at the end will be ignored.

Fields within a command are delimited by comma, multiple commands can be sent on one line delimited with a semi-colon. Eg.

FQREF,CURRENT;POWER?

Mandatory commands specified in the IEEE488.2 protocol have been implemented, (e.g. *IDN?, *RST) and all commands that expect a reply are terminated with a question mark (query).

The instrument maintains an error status byte consistent with the requirements of the IEEE488.2 protocol (called the standard event status register) that can be read by the mandatory command *ESR? (see section 5.1).

The instrument also maintains a status byte consistent with the requirements of the IEEE488.2 protocol, that can be read either with the IEEE488 serial poll function or by the mandatory command *STB? over RS232 or IEEE or LAN (see section 5.2).

The IEEE address defaults to 23 and can be changed via the COMMS menu.

The keyboard is disabled when the instrument is set to "remote" using the IEEE. Press HOME to return to "local" operation.

RS232 data format is: start bit, 8 data bits (no parity), 1 stop bit. Flow control is RTS/CTS (see section 5.2), baud rate is selectable via the MONITOR menu.

A summary of the available commands is given in the Appendix. Details of each command are given in the communication command section of the manual.

Commands are executed in sequence except for two special characters that are immediately obeyed:

- Control T (20) – reset interface (device clear)
- Control U (21) – warm restart

1.1 Standard event status register

PON		CME	EXE	DDE	QYE		OPC
-----	--	-----	-----	-----	-----	--	-----

- bit 0 OPC (operation complete)
cleared by most commands
set when data available or sweep complete
- bit 2 QYE (unterminated query error)
set if no message ready when data read
- bit 3 DDE (device dependent error)
set when the instrument has an error
- bit 4 EXE (execution error)
set when the command cannot be executed
- bit 5 CME (command interpretation error)
set when a command has not been recognised
- bit 7 PON (power on event)
set when power first applied or unit has reset

The bits in the standard event status register except for OPC are set by the relevant event and cleared by specific command (*ESR?, *CLS, *RST). OPC is also cleared by most commands that change any part of the configuration of the instrument (such as MODE or START).

1.2 Serial Poll status byte

		ESB	MAV	ALA			RDV
--	--	-----	-----	-----	--	--	-----

- bit 0 RDV (result data available)
set when results are available to be read as enabled by DAVER
- bit 3 ALA (alarm active)
set when an alarm is active and enabled by ALARMER
- bit 4 MAV (message available)
set when a message reply is waiting to be read
- bit 5 ESB (standard event summary bit)
set if any bit in the standard event status register is set as well as the corresponding bit in the standard event status enable register (set by *ESE).

1.3 RS232 connections

The RS232 port on the instrument uses the same pinout as a standard 9 pin serial port on a PC or laptop (9-pin male 'D' type).

Pin	Function	Direction
1	DCD	in (+ weak pull up)
2	RX data	in
3	TX data	out
4	DTR	out
5	GND	
6	DSR	not used
7	RTS	out
8	CTS	in
9	RI	not used

The instrument will only transmit when CTS (pin 8) is asserted, and can only receive if DCD (pin 1) is asserted. The instrument constantly asserts (+12V) DTR (pin 4) so this pin can be connected to any unwanted modem control inputs to force operation without handshaking. The instrument has a weak pull up on pin 1 as many null modem cables leave it open circuit. In electrically noisy environments, this pin should be driven or connected to pin 4.

To connect the instrument to a PC, use a 9 pin female to 9 pin female null modem cable:

1 & 6	-	4
2	-	3
3	-	2
4	-	1 & 6
5	-	5
7	-	8
8	-	7

1.4 Data format

Non integer results are sent as ASCII characters in a scientific format consisting of 5 or 6 digit mantissa plus exponent:

```
+1.2345+E00
+1.23456+E00
```

For higher speed transfer a proprietary binary format can be selected which compresses the data into 4 bytes, each of which is sent with the msb set to distinguish them from ASCII control characters. The data is sent as a 7 bit signed exponent, a mantissa sign, and a 20 bit mantissa:

byte	data
1	7 bit signed exponent +63 to -64
2	bit 6 = mantissa sign bit 5:0 = mantissa bit 19:14
3	mantissa bit 13:7
4	mantissa bit 6:0

The value is coded as a binary fraction between 0.5 and 0.9999..., a multiplier of 2^n and a sign ie:

$$\text{Value} = (\text{mantissa} / 2^{20}) \times 2^{\text{exponent}} \times -1^{\text{sign}}$$

value	equivalent	hex data transmitted
3.0	0.75×2^2	0x82,0xB0,0x80,0x80
0.1	0.8×2^{-3}	0xFD,0xB3,0x99,0xCD
-320	-0.625×2^9	0x89,0xE8,0x80,0x80

Any valid number would have the msb of the mantissa set; any number without the msb of the mantissa set is zero.

2 Communication commands

***CLS**

***CLS**

Function: Clear status

Description: Clears the *standard event status register*.

Format: *CLS

Arguments: none

Reply: none

Example: *CLS
*ESR?
0

Notes:

ESE**ESE**

Function:	Set standard event status enable register.
Description:	Enable which bits of the <i>standard event status register</i> set the ESB bit in the serial poll status byte..
Format:	*ESE, value
Arguments:	decimal equivalent of bits in standard event status enable register
Reply:	can be read by *ESE?
Example:	*ESE, 60
Notes:	The following bits in the standard event status enable register have been implemented: - bit 0 OPC (operation complete) - bit 2 QYE (unterminated query error) - bit 3 DDE (device dependent error) - bit 4 EXE (execution error) - bit 5 CME (command interpretation error) - bit 7 PON (power on event) For example, *ESE, 60 enables all the error bits so that the ESB bit in the serial poll status byte is set in the event of any error.

***ESR?**

***ESR?**

Function:	Standard event status register query
Description:	Returns the contents of the <i>standard event status register</i> and clears it.
Format:	*ESR?
Arguments:	none
Reply:	decimal equivalent of bits in standard event status register
Example:	*ESR? 33
Notes:	The following bits in the standard event status register have been implemented:

bit 0 OPC (operation complete)
 bit 2 QYE (unterminated query error)
 bit 3 DDE (device dependent error)
 bit 4 EXE (execution error)
 bit 5 CME (command interpretation error)
 bit 7 PON (power on event)

For example, if a command is sent incorrectly and is not recognised, the CME bit will be set and the value of 33 will be returned.

***IDN?**

***IDN?**

Function:	Identify query
Description:	Returns a standard format identification string.
Format:	*IDN?
Arguments:	none
Reply:	An ASCII string in the IEEE488.2 format: manufacturer,model,serial no,version
Example:	*IDN? NEWTONS4TH,PPA2530 KinetiQ, 01234,1.00
Notes:	

***OPC?**

***OPC?**

Function:	Test for operation complete
Description:	Returns 1 if previous operation is completed, 0 if not.
Format:	*OPC?
Arguments:	none
Reply:	0 or 1
Example:	START *OPC? 0 *OPC? 0 *OPC? 1
Notes:	*OPC? can be used to indicate when data is available or when a frequency sweep has completed.

***RST**

***RST**

Function:	Reset
Description:	Resets the instrument to the default state and clears the <i>standard event status register</i> .
Format:	*RST
Arguments:	none
Reply:	none
Example:	*RST
Notes:	The *RST command loads the default configuration. This is the same as loading the default configuration via the PROGRAM menu. Any preceding setup commands will be overwritten.

***SRE**

***SRE**

Function: Set service request enable register.

Description: Enable which bits of the *status byte register* initiate a service request.

Format: *SRE, value

Arguments: decimal equivalent of bits in status byte register

Reply: can be read by *SRE?

Example: *SRE, 1
generate a service request when data available.

Notes:

***SRE?**

***SRE?**

Function: Read service request enable register.

Description: Read back the present setting of the service request enable register.

Format: *SRE?

Arguments:

Reply: decimal equivalent of bits in status byte register that would generate a service request.

Example: *SRE?
1

Notes:

***STB?**

***STB?**

Function: Read serial poll status byte

Description: Returns the decimal value of the serial poll status byte.

Format: *STB?

Arguments: none

Reply: decimal value of the serial poll status byte

Example: *STB?
1

Notes: The following bits in the serial poll status register have been implemented:

- bit 0 RDV (results data available)
- bit 3 ALA (alarm active)
- bit 4 MAV (message available)
- bit 5 ESB (standard event summary bit)

***TRG**

***TRG**

Function:	Trigger
Description:	Initiates a new measurement, resets the range and smoothing.
Format:	*TRG
Arguments:	none
Reply:	none
Example:	MODE,VRMS *TRG VRMS,SURG?
Notes:	

***TST?**

***TST?**

Function: Self test query

Description: Returns the results of self test

Format: *TST?

Arguments: none

Reply: single integer
bit 0 – set if uncalibrated
bit 1 – set if error with analogue zero
> 15 – major system error

Example: *TST?
0

Notes:

***WAI**

***WAI**

Function: Wait for operation complete

Description: Suspends communication until the previous operation has completed

Format: *WAI

Arguments: none

Reply: none

Example: *TRG
*WAI
POWER,PHASE1?

Notes:

ABORT

ABORT

Function: Abort datalog
Description: Abort datalog data acquisition.
Format: ABORT
Arguments: none
Reply: none
Example: DATALOG, RAM, 0.02
START
wait for data values
ABORT

Notes:

ALARM

ALARM

Function: Set common controls for alarm1 and alarm2.

Description: Set the alarm latch and sounder control.

Format: *ALARM,latch,sounder*

Arguments: latch:
 ON
 OFF
 sounder:
 ENABLED
 DISABLED

Reply: none

Example: ALARM,ON,DISABLED

Notes:

ALARM?

ALARM?

Function:	Read alarm status.
Description:	Reads the status of the measurements and 2 alarms.
Format:	ALARM?
Arguments:	none
Reply:	single integer bit 0 data available bit 1 data error bit 2 alarm 1 bit 3 alarm 2
Example:	ALARM? 1
Notes:	An alarm is present if bit 0 is high (data is available) and either alarm 1 or alarm 2 bits are high.

ALARM1

ALARM1

Function: Set parameters for alarm1.

Description: Set alarm1 type and thresholds.

Format: *ALARM1,type,data,high,low*

Arguments: type:
 DISABLED
 HIGH
 LOW
 INSIDE
 OUTSIDE
 LINEAR
 data
 1-4
 high:
 high threshold
 low:
 low threshold

Reply: none

Example: *ALARM1,HIGH,1,2,0*

Notes: Both thresholds must be sent even if only one is used.

ALARM2

ALARM2

Function:	Set parameters for alarm2.
Description:	Set alarm2 type and thresholds.
Format:	<i>ALARM2,type,data,high,low</i>
Arguments:	type: DISABLED HIGH LOW INSIDE OUTSIDE data 1-4 for zoom data high: high threshold low: low threshold
Reply:	None
Example:	ALARM2,LOW,3,0,0.5
Notes:	Both thresholds must be sent even if only one is used. There is no LINEAR option for alarm 2.

ALARME

ALARME

Function:	Set alarm status enable register
Description:	Sets bits in the alarm status enable register to control which alarm bit if any set the alarm active bits in the status byte.
Format:	ALARME, <i>value</i>
Arguments:	decimal equivalent of alarm bits bit2 set bit 3 of status byte when alarm 1 is active bit3 set bit 3 of status byte when alarm 2 is active
Reply:	none
Example:	ALARME, 12 *SRE,8 set bit 3 in status byte when either alarm 1 or alarm 2 is active and generate a service request
Notes:	default value is 0

ALARME?

ALARME?

Function: Read alarm status enable register

Description: Read back present bits in the alarm status enable register which controls the alarm active bit in the status byte.

Format: ALARME?

Arguments: none

Reply: decimal equivalent of alarm bits

Example: ALARME?
12

Notes:

APPLIC**APPLIC**

Function: Select application mode.

Description: Some applications require special settings within the instrument for optimum measurement

Format: *APPLIC,type,setting*

Arguments: type:

NORMAL	
PWM	(PWM Motor Drive)
BALLAST	(Lighting ballast)
INRUSH	(Inrush Current)
POWERT	(Transformer mode)
STANDB	(Standby power)
CALIBR	(Calibration)

setting:

filter 0-2 (PWM only)

0:	4kHz
1:	1kHz
2:	250Hz

speed 0-3 (ballast only)

0:	fixed time
1:	fast
2:	medium
3:	slow

Reply: none

Example: *APPLIC,POWERT*
APPLIC,PWM,1

Notes:

BANDWI**BANDWI**

Function: Select bandwidth.

Description: The analogue bandwidth of the instrument can be selected as "wide" (to 3MHz). For low noise measurements at low frequency the bandwidth can be restricted to "low" (to 40kHz). For measurements of dc in the presence of large ac signal, the bandwidth can be further restricted to "dc only" (to 10Hz).

Format: `BANDWI,phase,type`

Arguments: phase:
 PHASE1
 PHASE2
 PHASE3
 type:
 WIDE
 LOW
 DONLY

Reply: none

Example: `BANDWI,WIDE`

Notes: Only use DONLY to improve accuracy of measurement of small dc in the presence of a large ac signal. For normal dc measurements use bandwidth = LOW.

BANDWI?

BANDWI?

Function: Read bandwidth setting.

Description: Returns a numerical value for the bandwidth setting.

Format: BANDWI,*phase?*

Arguments: phase:
 PHASE1
 PHASE2
 PHASE3

Reply: 0 = WIDE
 1 = LOW
 2 = DCONLY

Example: BANDWI,PHASE3,LOW
 BANDWI,PHASE3?
 1

Notes: If independent input control has not been enabled then the setting for phase 1 is used for all phases.

BEEP

BEEP

Function: Sound the buzzer
Description: Makes a “beep” from the instrument.
Format: BEEP
Arguments: none
Reply: none
Example: BEEP
Notes:

BLANKI

BLANKI

Function: Select blanking

Description: Enable or disable low value blanking.

Format: BLANKI,*value*

Arguments: value:
 ON
 OFF

Reply: none

Example: BLANKI,OFF

Notes:

CALVER**CALVER**

Function:	Load a calibration verification string.
Description:	When calibrated, the instrument stores a text string which can be read on the front panel (press SYS and LEFT). This shows the date of calibration. Users who subsequently verify the accuracy in their own calibration facilities can enter an alternative string with the new date. The original string is not overwritten but the alternative string is displayed instead.
Format:	CALVER, <i>string</i>
Arguments:	<i>string</i> is any sequence of printable alpha numeric characters. Use the underscore character to add a space between words. CALVER without a string argument clears the previously stored string.
Reply:	none
Example:	CALVER,12_DEC_2008_AMW
Notes:	As all white space is stripped from any communications string, the underscore character (ASCII 95 or 0x5F) must be used to space out the words. Underscore is shown as a space on the screen.

CALVER?

CALVER?

Function:	Read back the calibration verification string.
Description:	When calibrated, the instrument stores a text string which can be read on the front panel (press SYS and LEFT). This shows the date of calibration. Users who subsequently verify the accuracy in their own calibration facilities can enter an alternative string with the new date. The original string is not overwritten but the alternative string is displayed instead.
Format:	CALVER?
Arguments:	none.
Reply:	alphanumeric string
Example:	CALVER? 12_DEC_2008_AMW
Notes:	

CONFIG

CONFIG

Function:	Direct access of configuration parameters
Description:	Sets configuration parameter for which there may not be a direct command.
Format:	CONFIG, <i>index,data</i>
Arguments:	index is the number of the parameter data is the data for that parameter
Reply:	none
Example:	CONFIG,6,1 (set phase convention)
Notes:	The list of configurable parameters is given in the appendix. CONFIG goes through the same limit checking as when entering data from the menus.

CONFIG?

CONFIG?

Function:	Configurable parameter query
Description:	Reads the present value of a single parameter.
Format:	CONFIG, <i>index</i> ?
or:	CONFIG? <i>index</i>
Arguments:	<i>index</i> is the parameter number
Reply:	Value of parameter, real or integer as appropriate.
Example:	CONFIG,6? (read phase convention) 0 CONFIG,6,1 (set phase convention) CONFIG,6? 1
Notes:	The list of configurable parameters is given in the appendix.

COUPLI

COUPLI

Function:	Set ac or ac+dc coupling.
Description:	Selects the input coupling for a given input channel.
Format:	COUPLI, <i>phase,coupling</i>
Arguments:	phase: PHASE1 PHASE2 PHASE3 coupling: AC+DC ACONLY DCONLY
Reply:	none
Example:	COUPLI,PHASE2,AC+DC
Notes:	In multi phase applications, the coupling on phase 1 is applied to other phases unless "independent input control" is enabled.

COUPLI?

COUPLI?

Function:	Read ac/dc coupling setting.
Description:	Returns a numerical value for the coupling setting.
Format:	COUPLI, <i>phase,coupling</i>
Arguments:	phase: PHASE1 PHASE2 PHASE3
Reply:	0 = AC+DC 1 = AONLY 2 = DONLY
Example:	COUPLI,PHASE2,AC+DC COUPLI,PHASE2? 0
Notes:	In multi phase applications, the coupling on phase 1 is applied to other phases unless "independent input control" is enabled.

DATALO

DATALO

Function:	Set up datalog
Description:	Sets datalog parameters or accesses datalog non-volatile store.
Format:	<i>DATALO,function,interval,speed</i>
Arguments:	function: DISABLE RAM NONVOL RECALL DELETE interval: datalog interval in seconds speed: HIGH
Reply:	none
Example:	DATALOG,NONVOL,10 DATALOG,RAM,0,HIGH
Notes:	set interval to 0 to record every measurement as fast as possible. Set HIGH to select high speed mode for any combination of W, VA, VAr, pf, Vrms, Arms, and frequency. If HIGH is not sent then high speed mode is reset.

DATALO?

DATALO?

Function:	Read back datalog results
Description:	Return datalog values, one record per line, or the number of lines available
Format:	DATALO, <i>start,records?</i> DATALO,0? DATALO,LINES?
Arguments:	start: first record to return records: number of records to return 0: return all new records since last read
Reply:	3 to 6 data values depending on settings: index 1-n elapsed time in hours data1 data2 (if stored) data3 (if stored) data4 (if stored) one record per line
Example:	DATALOG,NONVOL,10 START wait for datalog STOP DATALOG,LINES? 30 DATALOG,21,3? 21,2.0000E-1,1.2345E0 22,2.1000E-1,5.6789E3 23,2.2000E-1,1.2345E0
Notes:	if no arguments are sent then DATALOG? returns all the available lines of data

DAV?

DAV?

Function:	Data available query
Description:	Returns data availability status.
Format:	DAV?
Arguments:	none
Reply:	Decimal equivalent of data available bits: bit0 new data available bit1 data available bit2 harmonic series data available bit3 efficiency data available bit6 integration data available bit7 datalog data available
Example:	SPEED,SLOW *TRG DAV? 0 DAV? 0 DAV? 0 DAV? 3 (data available)
Notes:	DAV? does not modify the status bits.

DAVER

DAVER

Function:	Set data available enable register
Description:	Sets bits in the data available enable register to control which status bits set the data available bits in the status byte.
Format:	DAVER, <i>value</i>
Arguments:	decimal equivalent of data available bits bit0 set bit 0 of status byte when new data available bit1 set bit 0 of status byte when data available
Reply:	none
Example:	DAVER, 1 set bit 0 in status byte when new data is available
Notes:	default value is 2: bit 0 of status byte is set whenever data is available.

DAVER?

DAVER?

Function: Read data available enable register

Description: Read back present setting of the data available enable register, which controls the status bits that set the data available bits in the status byte.

Format: DAVER?

Arguments: none

Reply: decimal equivalent of bits

Example: DAVER?
4

Notes:

DISPLAY

DISPLAY

Function:	Set the display page
Description:	Selects the page on the display so that the zoom data can be used for alarms.
Format:	DISPLAY, <i>page</i>
Arguments:	page: PHASE1 PHASE2 PHASE3 SUM NEUTRAL TOTAL FUNDAMENTAL VOLTAGE CURRENT
Reply:	None
Example:	DISPLAY,FUNDAMENTAL
Notes:	VOLTAGE is the same as TOTAL; CURRENT is the same as FUNDAMENTAL. They refer to the multiphase display modes.

DISPLAY?

DISPLAY?

Function: Read the displayed data

Description: Returns all the values presently on the screen.

Format: DISPLAY?

Arguments: none

Reply: Multiple floating point values separated by commas

Example: DISPLAY?

Notes:

EFFICI

EFFICI

Function: Set efficiency calculation

Description: Selects the data to be used for the efficiency calculation.

Format: *EFFICI,formula*

Arguments: formula:
 0 – disabled
 1 – phase 1 / phase 2
 2 – phase 2 / phase 1
 3 – slave / master
 4 – master /slave
 5 – mechanical sum
 6 – sum / mechanical
 7 – phase 3 / sum
 8 – sum /phase

Reply: none

Example: EFFICIENCY,2

Notes:

EFFICI?

EFFICI?

Function: Read efficiency result

Description: Reads back the total and fundamental efficiency results.

Format: EFFICI?

Arguments: none

Reply: 2 data values separated by commas:
total, fundamental

Example: EFFICI?
data returned

Notes:

FAST

FAST

Function: Set fast communications mode.

Description: Disables the screen drawing for high speed operation.

Format: FAST,*value*

Arguments: value:
ON
OFF

Reply: none

Example: FAST,ON

Notes: FAST mode does not suppress the data acquisition which continues in the background. See SUSPEND to disable all non-communication functions.

FQLOCK**FQLOCK**

Function:	Lock frequency.
Description:	Fix the frequency for analysis to the present value.
Format:	FQLOCK, <i>value</i>
Arguments:	value: ON OFF Normal Constant Dynamic
Reply:	none
Example:	FQLOCK,ON FQLOCK,Dynamic FQLOCK,Normal
Notes:	To fix the analysis to a specified frequency, first lock the frequency with FQLOCK,constant then send the desired frequency with the FREQUE command. ON is the same as CONSTANT OFF is the same as NORMAL

FQREF

FQREF

Function:	Set frequency reference.
Description:	Select the channel to be used for measuring the frequency.
Format:	<i>FQREF,phase</i> <i>FQREF,channel</i> <i>FQREF,phase,channel</i>
Arguments:	channel: voltage current speed phase: PHASE1 PHASE2 PHASE3
Reply:	none
Example:	FQREF,CURRENT
Notes:	Measured phase is always referred to phase 1 voltage no matter what channel is selected to measure the frequency, unless phase 1 is not active (eg phase 2 only mode).

FREQUE**FREQUE**

Function:	Set the analysis frequency
Description:	Sets the analysis frequency in Hz for frequency lock mode.
Format:	FREQUE, <i>frequency</i>
Arguments:	frequency in Hz
Reply:	none
Example:	FQLOCK,ON FREQUE,5e4 (set frequency to 50kHz)
Notes:	Lock the frequency with FQLOCK,ON before sending the desired frequency with the FREQUE command.

HARMON**HARMON**

Function: Set harmonic analyser mode.

Description: Set harmonic analyser mode and parameters.

Format: *HARMON,para,harmonic,max*

Arguments: para:
 THDD difference formula THD
 THDS harmonic series THD
 TIF Telephone Influence Factor
 THF Telephone Harmonic Factor
 TDD Total Demand Distortion
 TRD Total Rated Distortion
 HPHASE Series harmonic phase
 harmonic:
 individual harmonic for display
 max:
 length of harmonic series (to 100)

Reply: none

Example: *HARMON,THDS,3,50*

Notes: It is not necessary to send any arguments, but if any are sent they must be in the specified order.

HARMON?

HARMON?

Function:	Harmonic analyser query
Description:	Read harmonic results. Sets harmonic analyser mode if not already set. Waits for next unread data if necessary. Clears new data available bit read by DAV?
Format:	HARMON?
or:	HARMON, <i>phase</i> ?
or:	HARMON,SERIES?
or:	HARMON, <i>phase</i> ,SERIES?
Arguments:	phase: PHASE1 PHASE2 PHASE3 NEUTRAL PHASES
Reply:	11 data values separated by commas: freq,mag1,mag2,hmag1,hmag2,h%1, h%2,thd%1,thd%2,hphase1,hphase2
or:	magnitude and percentage for each harmonic, one channel per line
or:	magnitude and phase for each harmonic, one channel per line
Example:	HARMON,PHASE2? data returned
Notes:	HARMON? waits for next unread data.

HOLD

HOLD

Function: Set data hold

Description: Turns data hold on or off. Useful for reading data from different phases without it being changed between reads.

Format: HOLD,state

Arguments: state:
ON
OFF

Reply: none

Example: HOLD,ON
POWER,PHASE1,WATTS?
POWER,PHASE2,WATTS?
POWER,PHASE3,WATTS?
HOLD,OFF

Notes:

INPUT**INPUT**

Function: Set input mode

Description: Selects the input type of the instrument

Format: *INPUT,channel,type*

Arguments: channel:
 CH1
 CH2
 type:
 INTERN
 EXTATT
 EXTSHU

Reply: none

Example: INPUT,CH1,EXTSHU

Notes: CH1 applies to all voltage channels
 CH2 applies to all current channels

INTEGR**INTEGR**

Function:	Set integrated power mode.
Description:	Set integrated power mode, whether the integration for Watts and current use signed or unsigned values, and whether accumulated or averaged values are computed. Also sets up run time for integration over a specific interval.
Format:	<i>INTEGR,type,display</i> <i>INTEGR,RUNTIM,hours,minutes</i>
Arguments:	type: SIGNED MAGNITUDE display: TOTAL AVERAGE hours: integer minutes: integer
Reply:	none
Example:	INTEGR,MAGNITUDE,TOTAL
Notes:	

INTEGR?**INTEGR?**

Function:	Read integrated power mode.
Description:	Read integrated power mode for the selected phase.
Format:	INTEGR, <i>phase?</i>
Arguments:	phase: PHASE1 PHASE2 PHASE3 PHASES SUM
Reply:	13 values separated by commas time,Wh,WH.f,VAh,VAh.f,VArh,Varh.f pf,pf.f,V,V.f,Ah,Ah.f
Example:	START wait for integration time INTEGR,PHASE1? data returned
Notes:	INTEGR? without specifying the phase returns the appropriate single phase data.

KEYBOA

KEYBOA

Function:	Disable front panel keyboard.
Description:	The front panel keyboard can be disabled to prevent accidental operation.
Format:	KEYBOARD, <i>value</i>
Arguments:	value: ENABLE DISABLE
Reply:	none
Example:	KEYBOARD,DISABLE
Notes:	The keyboard can be re-enabled from the front panel only by pressing the HOME key.

LCR

LCR

Function: Set LCR meter mode.

Description: Set LCR mode and conditions.

Format: LCR,*parameter*

Arguments: parameter:
 AUTO
 CAPACITANCE
 INDUCTANCE
 IMPEDANCE

Reply: none

Example: LCR,IMPEDA

Notes:

LCR?

LCR?

Function:	LCR meter query
Description:	Read LCR meter results. Sets LCR meter mode if not already set. Waits for next unread data if necessary. Clears new data available bit read by DAV?
Format:	LCR, <i>phase?</i>
Arguments:	phase: PHASE1 PHASE2 PHASE3 PHASES
Reply:	11 data values separated by commas: freq, Vmag, Amag, impedance, phase, R, C, L, $\tan\delta$, Qf, reactance
Example:	LCR,IMPEDA LCR,PHASES? data returned
Notes:	LCR? waits for next unread data. LCR? without specifying the phase returns the appropriate single phase data.

LOWFRE**LOWFRE**

Function:	Set low frequency mode
Description:	Sets the low frequency option for extending the measurement window.
Format:	LOWFRE, <i>value</i>
Arguments:	value: ON OFF
Reply:	none
Example:	LOWFRE,ON
Notes:	LOWFRE is mainly used for measuring low frequencies (<5 Hz). However, as it applies digital filtering, it may also be useful when analysing any signals below a few hundred Hertz.

MODE**MODE**

Function: Set mode

Description: Sets the basic operating mode of the instrument.

Format: *MODE,type*

Arguments: type:
POWER (power meter)
INTEGR (integrator)
HARMON (harmonic analyser)
RMS (rms voltmeter)
LCR (LCR meter)
SCOPE (oscilloscope)
PHASEM (phase meter)

Reply: none

Example: *MODE,LCR*

Notes:

MSLAVE

MSLAVE

Function: Set master/slave mode

Description: Enables the instrument to synchronise with a second instrument to simultaneously measure up to 6 phases.

Format: MSLAVE,*type*

Arguments: *type*:
 DISABLE
 MASTER
 SLAVE
 SSLAVE

Reply: none

Example: MSLAVE,MASTER

Notes:

MULTIL**MULTIL**

Function: Selects data for multi string reply

Description: Selects data values across phases and functions that can be read in a single string.

Format: *MULTILOG,index,phase,function*

Arguments:

index:		
0	clear all	
1-64	select data 1-64	
phase:		
1-3	phase 1-3	
4	sum	
5	neutral	
function:		
1-99	see appendix C	

Reply: none

Example:

```
MULTIL,0
MULTIL,1,1,2      (phase 1 Watts)
MULTIL,2,2,2      (phase 2 watts)
MULTIL,3,4,3      (sum VA)
MULTIL?
3 data values returned
```

Notes:

For further information and assistance with the Multilog application please go to page 2-98 where you will find an application guide to assist with this function.

MULTIL?**MULTIL?**

Function:	Reads multi string reply	
Description:	Waits for data to be available (if required) then returns selected results. Either a single string or multiple string replies can be selected.	
Format:	MULTIL? MULTIL,<i>number</i>?	
Arguments:	number: The required number of data string replies	
Reply:	A single reply string containing up to 64 data values as selected by the MULTIL command. Multiple reply strings each containing the same number of data values (maximum of 64) as selected by the MULTIL command.	
Example:	MULTIL,0 MULTIL,1,1,2 (phase 1 Watts) MULTIL,2,2,2 (phase 2 Watts) MULTIL,3,4,3 (sum VA) MULTIL? In the above example a single string reply containing 3 data values is returned. MULTIL,10? In the above example 10 data strings are returned, each string containing 3 data values.	

Notes:

For further information and assistance with the Multilog application please go to page 2-98 where you will find an application guide to assist with this function.

NOOVER

NOOVER

Function:	Disable overranging
Description:	Prevents an overrange error from blanking out results in manual ranging.
Format:	NOOVER, <i>value</i>
Arguments:	value: ON OFF
Reply:	none
Example:	NOOVER,ON
Notes:	This can be useful when testing devices in a noisy environment. The range can be set to the correct range for the signal to be measured even if sporadic noise spikes would push it up on to the next range.

PFCNV

PFCNV

Function: Set power factor sign convention.

Description: Fundamental power factor is given a sign depending convention either:
 negative if lagging current
 negative if leading current

Format: PFCNV,*type*

Arguments: type:
 NEGLAG
 NEGLEA

Reply: none

Example: PFCNV,NEGLAG

Notes: An inductive load would have a lagging current, a capacitive load would have a leading current.
 The sign given to VAr can be independently set: see VARCON

PHASEM

PHASEM

Function: Set phase meter mode.

Description: Select phase meter mode and reference.

Format: PHASE,*reference*

Arguments: reference:
 CH1 ratio = ch2/ch1
 CH2 ratio = ch1/ch2

Reply: none

Example: PHASEM,CH2

Notes:

PHASEM?**PHASEM?**

Function:	Phase meter query
Description:	Reads phase meter results. Sets phase meter mode if not already set. Waits for next unread data if available. Clears new data available bit read by DAV?
Format:	PHASEM? PHASEM, <i>phase?</i>
Arguments:	phase: PHASE1 PHASE2 PHASE3 PHASES?
Reply:	5 data values separated by commas freq,mag1,mag2,dB,phase
Example:	PHASEM,CH1 PHASEM,PHASE1? data returned
Notes:	The phase convention can be set to 0° to -360°, 0° to +360°, or +180° to -180° in the SYSTEM menu or using PHCONV command. PHASEM? without specifying the phase returns the appropriate single phase data.

PHCONV

PHCONV

Function: Set phase convention

Description: Set phase convention

Format: PHCONV,*convention*

Arguments: convention:
 180: -180 to +180
 -360: 0 to -360
 +360: 0 to +360

Reply: none

Example: PHCONV, -360

Notes: 0 to -360 degrees is usually used for power analysis applications

POWER**POWER**

Function: Set up power analyser mode.

Description: Configure power analyser with sum
current display type

Format: POWER,*sum type*

Arguments: sum type:
TOTAL
AVERAGE

Reply: none

Examples: POWER,TOTAL

Notes:

POWER?**POWER?**

Function: Read power analyser results

Description: Reads back latest power analyser results.
Sets power analyser mode.
Waits for next unread data if necessary.
Clears new data available status bit.

Format: *POWER,phase,results?*

Arguments: phase:
 PHASE1
 PHASE2
 PHASE3
 PHASES
 SUM
 NEUTRAL (current only)
 results:
 WATTS
 VOLTAGE
 CURRENT
 VECTORS
 RMS
 WVA
 PH-PH

Reply: WATTS:
 freq,W,W.f,VA,VA.f,VAr,VAr.f,pf,pf.f,
 Wdc,W.h
 VOLTAGE or CURRENT:
 freq,rms,mag,dc,phase,pk,cf,mean,
 form factor,harm
 VECTORS:
 freq,vmag1,vlag1,amag1,alag1.....
 RMS:
 freq,vrms1,vdc1,arms1,adc1.....
 WVA:
 freq,w1,vrms1,arms1,w2.....

PH-PH:

freq,rms1,mag1,lag1,rms2...

Example: POWER,VECTORS?
data returned

Notes: POWER? without specifying the phase
returns the appropriate single phase data.
PHASES returns the data for all valid
phases 1-3.

PROGRA

PROGRA

Function: Access non volatile program stores.

Description: Recall, store or delete non-volatile program store.

Format: *PROGRA,function,number*

Arguments: function:
 RECALL
 STORE
 DELETE
 number
 0-100

Reply: none

Example: *PROGRA,RECALL,13*

Notes: Number 0 represents factory default, which can only be recalled.

PROGRA?

PROGRA?

Function:	Identify current program.
Description:	Reads the name of the last program to be loaded or recalled.
Format:	PROGRA?
Arguments:	none
Reply:	text string
Example:	PROGRA? factory default
Notes:	

RANGE

RANGE

Function:	Set channel ranging.
Description:	Select minimum range and range control for a given input channel.
Format:	<i>RANGE,channel,ranging,range</i>
Arguments:	channel: CH1 CH2 ranging: AUTO UPAUTO MANUAL range: range number 1-8
Reply:	none
Example:	RANGE,CH2,MANUAL,4
Notes:	CH1 sets the voltage range CH2 sets the current range Refer to the user manual for the range corresponding to each range number

RESOLU**RESOLU**

Function:	Set the data resolution
Description:	Data is returned in scientific format with exponent and mantissa. The resolution of the mantissa may be selected to be 5 digit (NORMAL) or 6 digit (HIGH) or 20 bit (BINARY).
Format:	RESOLU, <i>format</i>
Arguments:	format: NORMAL (5 digit mantissa) HIGH (6 digit mantissa) BINARY (compressed format)
Reply:	none
Example:	RESOLU,HIGH
Notes:	Data format for NORMAL is: [-]1.2345E[-]00 Data format for HIGH is: [-]1.23456E[-]00 The sign of the mantissa and exponent are only sent if negative shown as [-] in the above examples BINARY format encodes each non-integer value in a proprietary 4 byte format for higher speed data transfer. [Further notes on data format are included in section 1.4]

RESULT

RESULT

Function: Access non volatile results stores.

Description: Recall, store or delete non-volatile results.

Format: *RESULT,function,number*

Arguments: function:
 RECALL
 STORE
 DELETE
 number
 1-20

Reply: none

Example: RESULT,RECALL,13

Notes: There are 3 types of result: normal, harmonic and scope. Harmonic and scope results occupy 3 locations each.

RESULT?

RESULT?

Function: Identify used result stores.

Description: Reads a directory of the 20 non-volatile result locations.

Format: RESULT?

Arguments: none

Reply: 20 integers separated by commas

Example: RESULT?
0,0,1,3,-1,-1,0,2,-1,-1,0,0,0,0,0,0,0,0,0,0

Notes: 0 = empty
1 = normal result
2 = harmonic result
3 = scope result
-1 = continuation of previous

REZERO

REZERO

Function: Rezero front end

Description: Request the DSP to re-compensate for dc offset and compute a new autozero

Format: REZERO

Arguments: none

Reply: none

Example: REZERO

Notes:

SCALE

SCALE

Function:	Set channel scale factor.
Description:	Set a multiplying scale factor for a given input channel.
Format:	<i>SCALE,channel,factor</i>
Arguments:	channel: CH1 CH2 factor: multiplying scale factor
Reply:	none
Example:	SCALE,CH2,10
Notes:	CH1 sets the scale for all voltage channels CH2 sets the scale for all current channels

SCOPE?

SCOPE?

Function: Fetch raw scope data.

Description: Read back raw oscilloscope data.

Format: SCOPE,*channel*?
SCOPE,*phase,channel*?

Arguments: phase:
 PHASE1
 PHASE2
 PHASE3
 NEUTRA
 channel:
 VOLTAGE
 CURRENT

Reply: 252 signed integers:
 range
 trigger
 250 x data

Example: HOLD,ON
SCOPE,PHASE1,VOLTAGE?
read data
SCOPE,PHASE2,VOLTAGE?
read data
SCOPE,PHASE3,VOLTAGE?
read data
HOLD,OFF

Notes:

SCREEN?

SCREEN?

Function: Read the screen data

Description: Returns a bit map of screen pixel display in ascii and hex format

Format: SCREEN?

Arguments: none

Reply: Multiple data bit values

Example: SCREEN?
data returned

Notes: SCREEN? response:

ASCII coded Hex
(2 characters for each byte)
240 lines of 40 bytes (each line represents one line of the display)
preceded by #H
Each byte represents 8 dots where the lsb is the leftmost dot of the display
The bit is set for on and cleared for off

SETUP**SETUP**

Function:	Upload instrument set up
Description:	All the settings within the instrument may be read by SETUP? The same settings may then be stored by ending the same data back to the instrument. As it sends all settings in a compressed format it is quicker than setting individual parameters.
Format:	SETUP,index,data
Arguments:	index: 0-15 data: ASCII hex as returned by SETUP?
Reply:	none
Example:	SETUP? Read 16 lines of data SETUP,00,data00 SETUP,01,data01 . . SETUP,15,data15
Notes:	The settings are only updated when the 16 th line has been received and the checksum has been verified.

SETUP?

SETUP?

Function:	Read instrument set up
Description:	All the settings within the instrument may be read by SETUP?. The same settings may then be stored by ending the same data back to the instrument. As it sends all settings in a compressed format it is quicker than setting individual parameters.
Format:	SETUP?
Arguments:	none
Reply:	16 lines of ASCII data
Example:	SETUP? Read 16 lines of data
Notes:	

SHUNT**SHUNT**

Function: Set channel shunt value

Description: Set the resistance factor of an external current shunt to be divided into the measured voltage for a given input channel.

Format: SHUNT,*channel,resistance*

Arguments: channel:
 CH1
 CH2
 resistance:
 shunt resistance in Ohms

Reply: none

Example: SHUNT,CH1,10

Notes: The shunt value is set for all current channels

SMOOTH**SMOOTH**

Function:	Select the smoothing
Description:	Sets the filter time constant and dynamic response.
Format:	<i>SMOOTH,type,dynamics</i>
Arguments:	type: NONE NORMAL SLOW dynamics: AUTO FIXED
Reply:	none
Example:	SMOOTH,NORMAL,FIXED SMOOTH,NONE
Notes:	It is not necessary to send both parameters if it is only required to set the type. Both arguments must be sent to set the dynamics. FILTER is an alias for SMOOTH

SPEED

SPEED

Function:	Sets the measurement speed
Description:	Sets the minimum window size for the measurement.
Format:	<i>SPEED,value,window</i>
Arguments:	value: FAST MEDIUM SLOW VSLOW WINDOW
Reply:	none
Example:	SPEED,SLOW SPEED,WINDOW,0.1
Notes:	The window size argument is only needed for the SINDOW option

START

START

Function: Start datalog
Description: Initiate datalog data acquisition.
Format: START
Arguments: none
Reply: none
Example: DATALOG, RAM, 0.02
START
Notes:

STATUS?

STATUS?

Function:	Read back channel ranging status.
Description:	Read back condition of selected channel: range number (1-16) range text overflow/underflow status
Format:	STATUS?
or:	STATUS, <i>channel</i> ? STATUS? <i>channel</i>
Arguments:	channel: CH1 . . CH6
Reply:	range number,range text,over/under/ok 1-16 range as per RANGE command OVER if overflow LOW if underflow OK if in range
Example:	STATUS,CH1? 6,300V,OK STATUS? OK
Notes:	

STOP

STOP

Function: Stop datalog
Description: Stop datalog data acquisition.
Format: STOP
Arguments: none
Reply: none
Example: DATALOG, RAM, 0.02
START
wait for data values
STOP
read data values

Notes:

SUSPEN

SUSPEN

Function: Suspend data acquisition.

Description: Disable the data acquisition to maximise the communication speed.

Format: *SUSPEN,value*

Arguments: value:
 ON
 OFF

Reply: none

Example: FAST,ON
 SUSPEN,ON
 MULTILOG?
 SUSPEN,OFF
 FAST,OFF

Notes:

TEMPER

TEMPER

Function: Set up temperature measurement

Description: Set scaling and offset for a temperature sensor connected to the torque input (power transformer application mode)

Format: *TEMPER,type,scalefactor,offset*

Arguments: type:
 DISABLED
 CENTIG
 FARHEN
 scale:
 multiplying factor in degrees/Volt
 offset:
 additive zero in Volts

Reply: none

Example: TEMPER,CENTIG,5,-2
 sensor scaling = 5°C/V
 0V = 10°C

Notes:

TEMPER?

TEMPER?

Function: Read the temperature

Description: Returns the measured temperature from a sensor connected to the torque input

Format: TEMPER?

Arguments: none

Reply: single data value

Example: TEMPER?
data returned

Notes:

TORQSP**TORQSP**

Function:	Set up torque and speed measurement
Description:	Set scaling for torque and speed measurements
Format:	TORQSP, <i>type,torquescaling,speedscaling</i> TORQSP,OFFSET, <i>torqueoffset,speedoffset</i>
Arguments:	type: DISABLED ANALOG PULSED OFFSET
Reply:	none
Example:	TORQSP,PULSED,10,50 speed measured by pulse torque scaling = 10Nm/V 50 pulses/revolution
Notes:	If type = ANALOG then speed scaling is in rpm/V, if type = PULSED then speed scaling is pulses/rev Torque scaling is always Nm/V

TORQSP?

TORQSP?

Function:	Read the mechanical power
Description:	Returns measured mechanical data values
Format:	TORQSP?
Arguments:	none
Reply:	3 data values separated by commas: power, torque, speed
Example:	TORQSP? data returned
Notes:	

USER?

USER?

Function: Read the user data

Description: Returns up to 3 lines of user data

Format: USER?

Arguments: none

Reply: 3 lines of ASCII terminated by CR

Example: USER?
 Newtons4th Ltd
 R&D department
 KinetiQ #4

Notes:

VARCON

VARCON

Function:	Set VAr sign convention.
Description:	Fundamental VAr measurement is given a sign depending convention either: negative if lagging current negative if leading current
Format:	VARCON, <i>type</i>
Arguments:	type: NEGLAG NEGLEA
Reply:	none
Example:	VARCON,NEGLAG
Notes:	An inductive load would have a lagging current, a capacitive load would have a leading current. The sign given to power factor can be independently set: see PFCONV

VERSIO?

VERSIO?

Function:	Read the instrument code versions.
Description:	Returns an ASCII string with the details of the various parts of the instrument firmware.
Format:	VERSIO?
Arguments:	none
Reply:	date code, type, cpu, dsp, fpga, boot type: 0 – normal (30A) 2 – low current version (10A) 4 – high current version (50A)
Examples:	VERSION? KQ1306,0,1.10,1.10,1.10,1.01
Notes:	This data can be displayed on the screen by pressing SYSTEM then BACK

VRMS

VRMS

Function: Set up rms voltmeter.

Description: Set mode to rms voltmeter.

Format: VRMS

Arguments: none

Reply: none

Examples: VRMS

Notes: This has the same effect as MODE,VRMS

VRMS?**VRMS?**

Function:	Read true rms voltmeter results
Description:	Reads back latest voltmeter results. Waits for next unread data if necessary. Clears new data available status bit.
Format:	<i>VRMS,phase,results?</i>
Arguments:	results: RMS MEAN SURGE phase: PHASE1 PHASE2 PHASE3 PHASES
Reply:	RMS: 6 data values separated by commas Vrms,Arms,Vdc,Adc,Vac,Aac MEAN: 6 data values separated by commas Vrms,Arms,Vmean,Amean,Vff,Aff SURGE: 8 data values separated by commas Vrms,Arms,Vpk,Apk,Vcf,Acf, Vsurge1,Asurge
Example:	VRMS,PHASE1,RMS?
Notes:	VRMS? without specifying the phase returns the appropriate single phase data.

WIRING**WIRING**

Function:	Select wiring mode.																
Description:	Set wiring mode for computation of SUM and neutral data.																
Format:	WIRING, <i>type</i>																
Arguments:	type: <table> <tr> <td>SINGLE</td><td>(single ph 1)</td></tr> <tr> <td>2PHASE</td><td>(2 ph 2 wattmeter)</td></tr> <tr> <td>3PH2WA</td><td>(3 ph 2 wattmeter)</td></tr> <tr> <td>3PH3WA</td><td>(3 ph 3 wattmeter)</td></tr> <tr> <td>INDPH3</td><td>(3 ph 2 wattmeter + ph3)</td></tr> <tr> <td>PHASE1</td><td>(single ph 1)</td></tr> <tr> <td>PHASE2</td><td>(single ph 2)</td></tr> <tr> <td>PHASE3</td><td>(single ph 3)</td></tr> </table>	SINGLE	(single ph 1)	2PHASE	(2 ph 2 wattmeter)	3PH2WA	(3 ph 2 wattmeter)	3PH3WA	(3 ph 3 wattmeter)	INDPH3	(3 ph 2 wattmeter + ph3)	PHASE1	(single ph 1)	PHASE2	(single ph 2)	PHASE3	(single ph 3)
SINGLE	(single ph 1)																
2PHASE	(2 ph 2 wattmeter)																
3PH2WA	(3 ph 2 wattmeter)																
3PH3WA	(3 ph 3 wattmeter)																
INDPH3	(3 ph 2 wattmeter + ph3)																
PHASE1	(single ph 1)																
PHASE2	(single ph 2)																
PHASE3	(single ph 3)																
Reply:	none																
Examples:	WIRING,PHASE2																
Notes:	WIRING,SINGLE is the same as WIRING,PHASE1																

ZERO

ZERO

Function:	Apply or remove the zero
Description:	Applies or removes a zero function depending on the measurement mode (same as pressing ZERO key). Resets the integration data and timer if in power integration mode.
Format:	ZERO ZERO,DELETE
Arguments:	none
Reply:	none
Example:	ZERO
Notes:	

ZOOM**ZOOM**

Function:	Sets the display zoom parameters.
Description:	Sets the zoom level and data.
Format:	<i>ZOOM,level,data1,data2,data3,data4</i>
Arguments:	level: 0 – normal 1 – 2 line display (zoom level 1) 2 – single line display (zoom level 2) data1: - first data (zoom level 1) - or data for single line (zoom level 2) data2-4: - other data (zoom level 1) data consists of line number for channel 1 or line number + 128 for channel 2
Reply:	None
Example:	VRMS ZOOM,1,1,12 (level 1, ch1 rms, ch2 rms)
Notes:	It is not necessary to send all the parameters, but whatever parameters are sent must be in the correct order.

ZOOM?

ZOOM?

Function: Read the display zoom parameters.

Description: Reads the zoom level and data.

Format: ZOOM?

Arguments:

Reply: 5 integers separated by commas:
level:

0 – normal

1 – 2-4 value display (zoom level 1)

2 – single line display (zoom level 2)

data1-4:

zoom data

data consists of line number for channel 1
or line number + 128 for channel 2

Example: ZOOM?
1,1,129,0,0 (level 1, ch1 rms, ch2 rms)

Notes:

Multilog Application Guide **Configuring the N4L PPA Power Analyzer for** **Data logging**

The Multilog (MULTIL) command provides an excellent method for data logging up to 64 parameters of information via one query command - MULTIL?

The instrument will return a comma-separated string which relates to the MULTIL,X,X,X setup commands previously entered by the relevant communication method. This enables the system to send one query and return up to 64 different parameters, from different phases in one response.

Step 1.

Reset "MULTILOG" using the **MULTIL,0** command

This will clear any previously entered Multilog parameters and ensure the instrument does not return unwanted results.

Step 2.

Set up the Multilog parameters

The format of the Multilog command is as follows

MULTILOG, Index, Phase, function

Index is the order in which the value is returned (Effectively allocating a "slot" for the parameter in the returned string)

Phase is the phase (PH1,PH2,PH3 etc) from which the result should be acquired.

Function is the parameter type (eg. Watts, VAr, Frequency etc) of the return.

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The Function ID is chosen from Appendix C which is a continually growing list due to firmware upgrades of the power analyzers at N4L, at present the PPA2500 & PPA2600 have 78 possible functions:

Function	Measurement	Notes
1	frequency	
2	watts	
3	VA	
4	VAr	
5	power factor	
6	fundamental watts	
7	fundamental VA	
8	fundamental VAr	
9	fundamental PF	
10	harmonic watts	
11	harmonic watts %	
12	impedance	
13	resistance	

Example extract from the Multilog function list

Required Parameters

Order parameter to be returned within string	Phase (channel) of data returned	Parameter required
1	1	Frequency
2	1	Watts Phase 1
3	2	Watts Phase 2
4	3	Watts Phase 3
5	1	RMS Voltage Phase 1
6	2	RMS Voltage Phase 1
7	3	RMS Voltage Phase 1

MULTILOG Pattern

Command	Index	Phase	Function
MULTIL,	1	1	1
MULTIL,	2	1	2
MULTIL,	3	2	2
MULTIL,	4	3	2
MULTIL,	5	1	50
MULTIL,	6	2	50
MULTIL,	7	3	50

Command strings to sent, reference the above Multilog pattern;

MULTIL,0 // clears Multilog

MULTIL,1,1,1 // set Frequency as parameter 1

MULTIL,2,1,2 // set Phase 1 Watts as parameter 2

MULTIL,3,2,2 // set Phase 2 Watts as parameter 3

MULTIL,4,3,2 // set Phase 3 Watts as parameter 4

MULTIL,5,1,50 // set Phase 1 RMS Voltage as parameter 5

MULTIL,6,2,50 // set Phase 2 RMS Voltage as parameter 6

MULTIL,7,3,50 // set Phase 3 RMS Voltage as parameter 7

Step 3.

Send Multil query and read return string.

MULTIL? // returns a comma separated string as

Example return string:

5.0000E1, 2.4500E2, 2.4320E2, 2.5421E2, 1.0232E3, 1.0152E3, 1.0546E3

↑	↑	↑	↑	↑	↑	↑
Frequency	PH1 Watts	PH2 Watts	PH3 Watts	PH1 RMS Volt	PH2 RMS Volt	PH3 RMS Volt

Appendix – command summary

COMMAND SUMMARY

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command format	reply format
*CLS	
*ESE,value	
*ESE?	single integer data value
*ESR?	single integer data value
*IDN?	company,product,serial no,version
*OPC?	0 or 1
*RST	
*SRE,value	single integer data value
*SRE?	
*STB?	single integer data value
*TRG	
*TST?	single integer data value
*WAI	
ABORT	
ALARM,latch,sounder	
ALARM?	single integer data value
ALARME,value	
ALARME?	single integer data value
ALARM1,type,data,high,low	
ALARM2,type,data,high,low	
APPLIC,type,setting	
BANDWI,phase,type	
BEEP	
BLANKI,on/off,threshold	
CALVER,string	
CALVER?	string
CONFIG,parameter,data	
CONFIG,parameter?	single integer or real data value
COUPLI,phase,coupling	
DATALO,func,interval,speed	
DATALO,LINES?	single integer
DATALO,0?	index,time,data... one record per line
DATALO,start,records?	index,time,data... one record per line
DAV?	single integer data value
DAVER,value	
DAVER?	single integer data value
DISPLAY,page	
DISPLAY?	multiple real data values
EFFICI,type	
EFFICI?	total efficiency, fundamental efficiency
FAST,on/off	

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FQLOCK,on/off	
FQREF,phase,channel	
FREQUE,frequency	
HARMON,para,h,hmax	
HARMON,phase?	freq,mag1,mag2,hmag1,hmag2,h1,h2,
or	thd1,thd2,hphase1,hphase2
HARMON,phase,SERIES?	mag,%, x n harmonics
or	mag,phase, x n harmonics
HOLD,on/off	
INPUT,channel,type	
INTEGR,type,display	
INTEGR,RUNTIM,hours,mins	
INTEGR,phase?	time,Wh,Wh.f, VARh,VARh.f,VAh,VAh.f, pf,pf.f,Vav,Vav.fAh,Ah.f
KEYBOA,value	
LCR,conditions,param,head	
LCR,phase?	freq,mag1,mag2,impedance,phase,R, L,C (series),R,L,C (parallel),tan δ ,Q
LOWFRE,on/off	
MODE,type	
MSLAVE,type	
MULTILOG,index,phase,func	
MULTILOG?	1-30 floats as selected
PFCNV,convention	
PHASEM,ratio	
PHASEM,phase?	freq,mag1,mag2,dB,phase
PHCONV,convention	
POWER,sum A	
POWER,PHASE,WATTS?	freq,W,W.f, VA,VA.f,VAR,VAR.f,pf,pf.f, Wdc,W.h
POWER,PHASE,VOLTAGE?	freq,rms,mag,dc, ϕ ,peak,cf,mean,ff, harmonic
POWER,PHASE,CURRENT?	freq,rms,mag,dc, ϕ ,peak,cf,mean,ff, harmonic
POWER,PH-PH?	freq,rms1,mag1, ϕ 1,rms2,mag2, ϕ 2, rms3,mag3, ϕ 3
POWER,RMS?	freq,vrms1,vdc1,arms1,adc1,vrms2, vdc2,arms2,adc2,vrms3,vdc3, arms3, adc3
POWER,VECTORS?	freq,mag1, ϕ 1,mag2, ϕ 2,mag3, ϕ 3, mag4, ϕ 4,mag5, ϕ 5,mag6, ϕ 6
POWER,WVA?	freq,w1,vrms1,arms1,w2,vrms2, arms2,w3,vrms3,arms3

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PROGRAM,function,number	
PROGRAM?	CR terminated text string
RANGE,ch,ranging,range	
RESOLU.format	
RESULT,function,number	
RESULT	multiple integers
REZERO	
SCALE,channel,factor	
SCALE,channel?	single real data value
SCOPE,PHASE,v/a?	range, trigger, 250 signed integer values
SHUNT,channel,resistance	
SHUNT,channel?	single real data value
SMOOTH,type,dynamics	
SPEED,value>window	
START	
STATUS,channel?	range number,range text,over/low/ok
STOP	
STREAM,enable>window	
STREAM,disable	
STREAM?	data, data, data, data, data,
SUSPEN,on/off	
TEMPER,type,scale,offset	
TEMPER?	single real data value
TORQSP,type,tscale,sscale	
TORQSP,OFFSET,toff,soff	
TORQSP?	mechanical power, torque, speed
USER?	3 CR terminated text strings
VARCON,convention	
VERSION?	datecode,cpu,dsp,fpga,boot
VRMS	
VRMS,PHASE,RMS?	rms1,rms2,dc1,dc2,ac1,ac2
VRMS,PHASE,MEAN?	rms1,rms2,mean1,mean2,ff1,ff2
VRMS,PHASE,SURGE?	pk1,pk2,cf1,cf2,surge1,surge2
WIRING,configuration	
ZERO	
ZERO,DELETE	
ZOOM,level,d1,d2,d3,d4	
ZOOM?	level,d1,d2,d3,d4

calibration commands

CALAPP	
CALCOM,freq	
CALFIL,index,value	
CALFIL?	Six real data values
CALFRQ,index,freq	
CALFRQ?	Seven real data values
CALIBR,index,value,inputs	
CALIBR?	Single integer data value
CALIDS,string	
CALIDS?	String
CALJIG,value	
CALMOD,value	
CALPHA,index,inputs	
CALRES	
CALSAV,password	
CALSYS,index,value,inputs	
CALSNO,serial number	
CALSTR,string	
CALSTR?	String
CALTQS,index,value	
CALTQS?	Four real data values
CALVER,string	
CALVER?	String

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Appendix B – Configurable parameters

All parameters can be accessed using the CONFIG command:

CONFIG, <i>number,parameter</i>		
<i>number</i>	Function	<i>parameter</i>
1	Operating mode,	(sets Main Mode) 0=RMS Voltmeter 1=Phase Meter 2=Power Analyser 3=Impedance Analyser 4=Power Integrator 5=Harmonic Analyser 7=Oscilloscope
3	Master/slave,	(Aux control) 0=Disabled 1=Master 2=Slave 3=Sslave
4	Autozero manual or auto,	(System options) 0=Auto 1=Manual
5	Low blanking,	(System options) 0=Off 1=On
6	Phase convention,	(System options) 0=-180° to +180° 1=0° to -360° 3=0° to +360°
7	Frequency lock on/off,	(Acquisition advance options) 0=Normal 1=Constant 2=Dynamic
8	Graph,	(System options) 0=Dots 1=Lines

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- 9 Keyboard beep on/off, (System options)
 0=Off
 1=On
- 10 Ignore overload, (Acquisition advance options)
 0=Off
 1=On
- 11 Low frequency mode, (Acquisition control)
 0=Off
 1=On
- 12 Window size, (Acquisition control, speed-window)
 0=ms
 1=Sec's
- 13 Speed, (Acquisition control)
 0=Very Slow
 1=Slow
 2=Medium
 3=Fast
 4=Window
- 14 Smoothing (Acquisition Control)
 0=Normal
 1=Slow
 2=None
- 15 Smoothing Response (Acquisition Control)
 0=Auto reset
 1=Fixed time
- 16 Baud rate, (Remote options , RS232)
 0=19200
 1=9600
 2=4800
 3=2400
 4=1200
- 18 LAN IP address nibble 3, (Remote options - LAN - enter figure as required)
- 19 LAN IP address nibble 2, (Remote options - LAN - enter figure as required)
- 20 LAN IP address nibble 1, (Remote options - LAN - enter figure as required)
- 21 LAN IP address nibble 0, (Remote options - LAN - enter figure as required)

- 22 Independent input control, (System options)
 0=Disabled
 1=Enabled
- 24 Enable channel 1, (Range – voltage input)
 0=Internal
 3=External Attenuator
- 25 Enable channel 2, (Range – current input)
 0=Internal
 2=External Shunt
- 26 Input range channel 1, (Range – minimum range voltage)
 0=1v
 1=3v
 2=10v
 3=30v
 4=100v
 5=300v
 6=1Kv
 7=3kV
- 27 Input range channel 2, (Range – minimum range current)
 0=100ma
 1=300ma
 2=1A
 3=3A
 4=10A
 5=30A
 6=100A
 7=300A
- 28 Input ranging channel 1, (Range – autoranging voltage)
 0=Full Autorange
 1=Autorange up
 2=Manual
- 29 Input ranging channel 2, (Range – autoranging current)
 0= Full Autorange
 1=Autorange up
 2=Manual

- 30 Coupling, (Coupling)
 0=ac+dc
 1=ac
 2=dc
- 31 Bandwidth, (Coupling - bandwidth)
 0=Wide (dc-2MHz)
 1=Low (dc-30KHz)
 2=dc (dc-5Hz)
- 32 Scale factor channel 1 voltage, (Ranging - Enter figures as required)
- 33 Scale factor channel 1 current, (Ranging - Enter figures as required)
- 34 External attenuator channel 1, (Ranging - voltage input - attenuator ratio as required)
- 35 External shunt channel 1, (Ranging - current input - resistance value as required)
- 38 Resolution, (remote options - digit resolution)
 0=Normal
 1=High
 2=Binary
- 39 Frequency reference phase, (Acquisition control)
 0=Phase 1
 1=Phase 2
 2=Phase 3
- 40 Frequency reference voltage/current, (Acquisition control)
 0=Voltage
 1=Current
 2=Speed
- 41 Display page, (Main display)
 0=Phase 1 page
 1=Phase 2 page
 2=Phase 3 page
 3=Sum page
 4=Phase 1,2 &3 page
 5=Phase 1,2 & 3 fundamentals page
 6=NEU page

- 42 Zoom level, (Main display)
 0=Zoom –
 1=Zoom +
 2=second Zoom +
- 43 Function zoomed on 1, (Main display)
 0=Voltage, Current & Frequency
 1=Watts, Current, Voltage & Frequency
 2= VA, Current, Voltage & Frequency
 3= VAr, Current, Voltage & Frequency
 4= pf, Current, Voltage & Frequency
- 44 Function zoomed on 2, (Main display)
 0=Current & Frequency
 1= Watts, Current & Frequency
 2= VA, Current & Frequency
 3= VAr, Current & Frequency
 4= pf, Current & Frequency
 5= Current, Voltage & Frequency
- 45 Function zoomed on 3, (Main display)
 0= Watts & Frequency
 2= Watts, VA & Frequency
 3= Watts, VAr & Frequency
 4= Watts, pf & Frequency
 5= Watts, Voltage & Frequency
 6= Watts, Current & Frequency
- 46 Function zoomed on 4, (Main display)
 0= Watts & VA
 3= Watts, VA & VAr
 4= Watts, VA & pf
 5= Watts, VA & Voltage
 6= Watts, VA & Current
 7= Watts, VA & Frequency
 8= Watts, VA & Harmonic
 9= Watts, VA & dc watts
 10= Watts, VA & V Ph-Ph

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- 47 Datalog display type, (Datalog display information mode)
 0=Real Time
 1=Table
 2=Graph
- 48 Manual frequency, (Acquisition advance options – frequency lock on)
 0=Frequency in μ hz
 1=Frequency in Hz
- 49 DFT selectivity, (Acquisition advance options)
 0=Normal
 1=Narrow
- 50 Program 1-6 direct load, (System options)
 0=Disabled
 1=Enabled
- 52 Frequency filter, (Acquisition control)
 0=Disabled
 1=Enabled
- 53 Phase angle reference, (Acquisition control)
 0=Voltage
 1=Current
- 54 Datalog Zoom1, (Datalog-RAM)
 0=Enabled
 1=Disabled
- 55 Datalog Zoom2, (Datalog-RAM)
 0=Enabled
 1=Disabled
- 56 Datalog Zoom3, (Datalog-RAM)
 0=Enabled
 1=Disabled
- 57 Datalog Zoom4, (Datalog-RAM)
 0=Enabled
 1=Disabled

- 58 Datalog memory type, (Datalog)
 0=Disabled
 1=RAM
 2=Non Volatile
- 59 Datalog interval, (Datalog – Enter time required)
- 61 Formula, (Maths)
 0=Disabled
 1=(term1 + term2/term3 + term4)
 2=(term1 + term2) x term3/term4
 3=term1 x term2/(term3 + term4)
- 62 Argument term 1 (Maths)
 0=Disabled
 1=Constant
 2=Voltage
 3=Current
 4=Torque
 5=Speed
- 63 Sub argument term 1, (For voltage and current arguments only)
 0=rms
 1=dc
 2=ac
 3=Fundamental
 4=Peak
 5=Mean
 6= Ph-Ph rms
 7=Ph-Ph mag
- 64 Term 1 coefficient, (Enter value)
- 65 Argument term 2,
 0=Disabled
 1=Constant
 2=Voltage
 3=Current
 4=Torque
 5=Speed

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- 66 Sub argument term 2, (For voltage and current arguments only)
0=rms
1=dc
2=ac
3=Fundamental
4=Peak
5=Mean
6= Ph-Ph rms
7=Ph-Ph mag
- 67 Term 2 coefficient, (Enter value)
- 70 application mode,
0=Normal
1=PWM motor Drive
2=Lighting ballast
3=Inrush current
4=Power transformer
5=Standby power
- 71 Frequency filter, (Application options mode - PWM Motor Drive)
0=4KHz
1=1KHz
2=250Hz
- 72 Frequency tracking speed, (Application options mode - Lighting Ballast)
0=Fixed time
1=Fast
2=Medium
3=Slow
- 73 Low frequency, (Application options mode - PWM Motor Drive)
0=Off
1=On
- 74 Argument term 3 (Maths)
0=Disabled
1=Constant
2=Voltage
3=Current
4=Torque
5=Speed

- 75 Sub argument term 3, (For voltage and current arguments only)
 0=rms
 1=dc
 2=ac
 3=Fundamental
 4=Peak
 5=Mean
 6= Ph-Ph rms
 7=Ph-Ph mag
- 76 Term 3 coefficient, (Enter value)
- 77 Argument term 4 (Maths)
 0=Disabled
 1=Constant
 2=Voltage
 3=Current
 4=Torque
 5=Speed
- 78 Sub argument term 4, (For voltage and current arguments only)
 0=rms
 1=dc
 2=ac
 3=Fundamental
 4=Peak
 5=Mean
 6= Ph-Ph rms
 7=Ph-Ph mag
- 79 Term 4 coefficient, (Enter value)
- 80 Temperature, (Applications – Power Transformer)
 0=Disabled
 1=°C
 2=°F
- 81 Master/Slave-Sum watts, (Aux control–Master/Slave-Master)
 0=Master
 1=Master + Slave

- 82 Wiring configuration, (Acquisition control)
 0=Single phase 1
 1=2 phase 2 wattmeter
 2=3 phase 2 wattmeter
 3=3 phase 3 wattmeter
 4=Single phase 2
 5=Single phase 3
 6=3 phase 2 wattmeter + PH3
- 83 Integration, (Power analyzer - Power integrator)
 0=Signed
 1=Magnitude
- 84 Torque + speed, (Application options – PWM motor drive)
 0=Disabled
 1=Analogue speed
 2=Pulsed speed
- 85 Torque scaling Nm/V, (Enter Nm/v value) or (Temperature °/v value)
- 86 Speed scaling Hz/V, (Enter rpm/v value)
- 87 Pulses per revolution, (Enter pulses/rev value)
- 88 Integration display, (Mode - Power integrator)
 0=Total
 1=Average
- 89 Sum current average, (Power analyzer)
 0=Total
 1=Average
- 90 Phase 3 reference, (Acquisition control – 3 phase 2 wattmeter + PH3)
 0=Voltage
 1=Current
 2=ac line
 3=Phase 1 & 2
- 91 Power factor sign, (Power analyzer)
 0=Negative lagging
 1=Negative leading

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- | | |
|-----|---|
| 92 | VAr sign, (Power analyzer) |
| | 0= Negative lagging |
| | 1=Negative leading |
| 93 | Efficiency computation, (Power analyzer) |
| | 0=Disabled |
| | 1=Phase 1 / Phase 2 |
| | 2=Phase 2 / Phase 1 |
| | 3=Slave/Master |
| | 4=Master/Slave |
| | 5=Mechanical/Sum |
| | 6=Sum/Mechanical |
| | 7=Phase 3/Sum |
| | 8=Sum/Phase 3 |
| 94 | Range lock across phases, (Range – when acquisition is using 3 phases) |
| | 0=Disabled |
| | 1=Enabled |
| 95 | Torque offset, (Application options mode – PWM motor drive – Nm offset value) |
| | (Application options mode –Power transformer - Temperature– offset value) |
| 96 | Speed offset, (Application options mode – PWM motor drive – rpm offset value) |
| 99 | Computation mode, (Harmonic analyzer) |
| | 0=Difference formula |
| | 1=Harmonic series |
| | 2=TIF |
| | 3=THF |
| | 4=TRD |
| | 5=TDD |
| | 6=Series harmonic phase |
| 100 | Selected harmonic, (Harmonic analyzer - figure = harmonic required) |
| 101 | Harmonic series up to, (Harmonic analyzer - figure = harmonic max) |
| 102 | Bargraph scale, (Harmonic analyzer - figure = % required) |
| 103 | Current rating (TRD), (Harmonic analyzer – TRD mode – enter figure) |
| 106 | Timebase, (Scope - Enter figure/div) |

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- 107 trigger level, (Scope - Enter figure/div)
- 108 Pretrigger, (Scope)
0=None
1=25%
2=50%
3=75%
- 109 trigger polarity, (Scope)
0=Rising edge
1=Falling edge
- 110 trigger type, (Scope)
0=Auto
1=Normal
2=Single shot
- 111 trigger reference, (Scope)
0=Voltage
1=Current
- 112 trigger phase, (Scope)
0=Phase 1
1=Phase 2
2=Phase 3
- 113 cursors enable, (Scope)
0=Off
1=On
- 114 trigger HF reject, (Scope)
0=Off
1=On
- 119 zoom 2 high resolution, (System)
0=Disabled
1=Enabled
- 122 Auxiliary device, (Aux control)
0=None
6=PCIS

- 128 Switch phase offset, (Aux control – PCIS device)
 0=0°
 1=45°
 2=90°
 3=135°
 4=180°
 5=225°
 6=270°
 7=315°
- 129 Switch on cycles, (Aux control – PCIS device)
 0=Single cycle
 1=Continuous
 2=Half cycle
- 130 Gear ratio, (Aux control – frequency reference – speed - Enter ratio value)
 Gear ratio, (Aux control – frequency reference – speed - Enter ratio value)
- 131 3 Phase 2 Wattmeter VA, VAr Option, (Power Analyser)
 0=Low distortion
 1=High Distortion
- 132 Integrator-run time (Hours), (Mode – Power integrator - enter figure)
- 133 Integrator-Run time (mins), (Mode - Power integrator – enter figure)
- 134 Ph – Ph Measurement, (Power analyser)
 0=Rms
 1=Mean
- 135 Difference THD, (Power analyser)
 0=Disabled
 1=Enabled
- 136 Master/Slave Mechanical, (Aux control – Master/slave-Master)
 0=Master
 1=Slave
- 137 Parameter, (Impedance analyzer)
 0=Auto
 1=Capacitance
 2=Inductance
 3=Impedance

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- 138 **Model,** (Impedance analyzer – auto parameter)
 0=Series
 1=Parallel
- 139 **Phase offset,** (Impedance analyzer - Enter figures)
- 148 **dB offset,** (Phase meter - Enter figures)
- 150 **Ratio,** (Phase meter)
 0=ch2/ch1
 1=ch1/ch2
- 152 **RS232 printer enable,** (Remote options)
 0=Disabled
 1=Enabled
- 153 **IEEE address,** (Remote options – GPIB mode – enter address figures)
- 154 **Interface,** (Remote options)
 0=RS232
 1=LAN
 2=GPIB
 3=USB
- 155 **Recall with program,** (Remote options)
 0=Off
 1=On
- 156 **Alarm 1 data,** (Alarm options)
 0=Zoom1
 1=Zoom 2
 2=Zoom3
 3=Zoom 4
- 157 **Alarm 1 type,** (Alarm options)
 0=Disabled
 1=Linear
 2=Alarm if high
 3=Alarm if low
 4=Outside window
 5=Inside window

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- 158 Alarm 1 high threshold, (Alarm options – alarm if high – enter figure)
- 159 Alarm 1 low threshold, (Alarm options – alarm if low – enter figure)
- 160 Alarm latch, (Alarm options – alarm if high)
0=Off
1=On
- 161 Alarm sounder, (Alarm options – alarm if high)
0=Enabled
1=Disabled
- 167 Alarm 2 data, (Alarm options)
0=Zoom1
1=Zoom 2
2=Zoom 3
3=Zoom 4
- 168 Alarm 2 type, (Alarm options)
0=Disabled
1=Linear
2=Alarm if high
3=Alarm if low
4=Outside window
5=Inside window
- 169 Alarm 2 high threshold, (Alarm options – alarm if high – enter figure)
- 170 Alarm 2 low threshold, (Alarm options – alarm if low – enter figure)
- 176 Enable channel 3, (Range – voltage input)
0=Internal
3=External attenuator
- 177 Enable channel 4, (Range – current input)(Sys independent ranging enabled)
0=Internal
2=External shunt

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- 178 Input range channel 3, (Range – minimum range voltage)
 0=1v
 1=3v
 2=10v
 3=30v
 4=100v
 5=300v
 6=1Kv
 7=3kV
- 179 Input range channel 4, (Range – minimum range current)
 0=100ma
 1=300ma
 2=1A
 3=3A
 4=10A
 5=30A
 6=100A
 7=300A
- 180 Input ranging channel 3, (Range – autoranging voltage)
 0=Full Autorange
 1=Autorange up
 2=Manual
- 181 Input ranging channel 4, (Range – autoranging current)
 0= Full Autorange
 1=Autorange up
 2=Manual
- 182 Coupling phase 2, (Coupling)
 0=ac +dc
 1=ac
 2=dc
- 183 Bandwidth phase 2, (Coupling - bandwidth)
 0=Wide (dc-2MHz)
 1=Low (dc-30KHz)
 2=dc (dc-5Hz)
- 184 Scale factor channel 3 voltage, (Ranging - Enter figures as required)
- 185 Scale factor channel 4 current, (Ranging - Enter figures as required)

- 186 External attenuator channel 3, (Ranging – voltage input - attenuator ratio as required)
- 187 External shunt channel 4, (Ranging – current input – resistance value as required)
- 200 Enable channel 5, (Range – voltage input)
0=Internal
3=External attenuator
- 201 Enable channel 6, (Range – current input)
0=Internal
2=External shunt
- 202 Input range channel 5, (Range – minimum range voltage)
0=1v
1=3v
2=10v
3=30v
4=100v
5=300v
6=1Kv
7=3kV
- 203 Input range channel 6, (Range – minimum range current)
0=100ma
1=300ma
2=1A
3=3A
4=10A
5=30A
6=100A
7=300A
- 204 Input ranging channel 5, (Range – autoranging voltage)
0=Full Autorange
1=Autorange up
2=Manual
- 205 Input ranging channel 6, (Range – autoranging current)
0= Full Autorange
1=Autorange up
2=Manual

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- 206 Coupling phase 3, (Coupling)
 0=ac +dc
 1=ac
 2=dc
- 207 Bandwidth phase 3, (Coupling - bandwidth)
 0=Wide (dc-2MHz)
 1=Low (dc-30KHz)
 2=dc (dc-5Hz)
- 208 Scale factor channel 5 voltage, (Ranging - Enter figures as required)
- 209 Scale factor channel 6 current, (Ranging - Enter figures as required)
- 210 External attenuator channel 5, (Ranging – voltage input - attenuator
 ratio as required)
- 211 External shunt channel 6, (Ranging – current input – resistance value as
 required)

Appendix C – MULTILOG parameters

function	measurement	notes
1	frequency	
2	watts	
3	VA	
4	VA _r	
5	power factor	
6	fundamental watts	
7	fundamental VA	
8	fundamental VA _r	
9	fundamental PF	
10	harmonic watts	
11	harmonic watts %	
12	impedance	Imp meter mode
13	resistance	Imp meter mode
14	reactance	Imp meter mode
15	impedance phase	Imp meter mode
16	efficiency	
17	fundamental efficiency	
18	maths	
19	integrated watts	integrator mode
20	integrated VA	integrator mode
21	integrated VA _r	integrator mode
22	integrated rms current	integrator mode
23	average power factor	integrator mode
24	integrated fundamental watts	integrator mode
25	integrated fundamental VA	integrator mode
26	integrated fundamental VA _r	integrator mode
27	integrated fundamental current	integrator mode
28	average fundamental power factor	integrator mode
29	average integrated watts	integrator mode
30	average integrated VA	integrator mode
31	average integrated VA _r	integrator mode
32	average integrated fundamental watts	integrator mode
33	average integrated fundamental VA	integrator mode
34	average integrated fundamental VA _r	integrator mode
35	average rms voltage	integrator mode
36	average fundamental voltage	integrator mode
37	Standby mode frequency	
38	DC watts	

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39	average rms current	integrator mode
40	average fundamental current	integrator mode
41	reserved for future expansion	
42	reserved for future expansion	
43	elapsed time	integrator mode
44	reserved for future expansion	
45	reserved for future expansion	
46	reserved for future expansion	
47	reserved for future expansion	
48	reserved for future expansion	
49	reserved for future expansion	
50	rms voltage	
51	rms current	
52	fundamental voltage	
53	fundamental current	
54	voltage phase	
55	current phase	
56	harmonic voltage	
57	harmonic current	
58	dc voltage	
59	dc current	
60	ac voltage	
61	ac current	
62	peak voltage	
63	peak current	
64	voltage crest factor	
65	current crest factor	
66	rectified mean voltage	
67	rectified mean current	
68	voltage form factor	
69	current form factor	
70	voltage harmonic	harmonic mode
71	current harmonic	harmonic mode
72	voltage harmonic percentage	harmonic mode
73	current harmonic percentage	harmonic mode
74	voltage thd	harmonic mode
75	current thd	harmonic mode
76	voltage tif	harmonic mode
77	current tif	harmonic mode
78	phase to phase rms voltage	
79	phase to phase fundamental voltage	
80	phase to phase voltage phase angle	
81	phase to phase rms voltage	

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82	voltage surge	
83	current surge	
84	voltage rms deviation	transformer mode
85	voltage fundamental deviation	transformer mode
86	voltage phase deviation	transformer mode
87-99	reserved for future expansion	

Note: Functions 78 and 81 are the same.

Phase selection:

- 1 = phase 1
- 2 = phase 2
- 3 = phase 3
- 4 = sum
- 5 = neutral

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There are some special functions:

Measurement (function)	phase	Previous function
mechanical speed in Hz	neutral	dc voltage (function 58)
mechanical speed in rpm	neutral	ac voltage (function 60)
torque in Nm	neutral	rms voltage (function 50)
mechanical power	neutral	Watts (function 2)

Notes:

These special functions must use the Neutral Phase (Phase 5)

Due to the limited number of function numbers available these Special functions re-use function numbers that apply to other measurements for Phases 1 to 3.

Examples for setting up individual special function measurements:

- > multil,0 Setting to clear any previous data
- > multil,1,5,58 Setting for Mechanical speed in Hz
- > multil,1,5,60 Setting for Mechanical speed in rpm
- > multil,1,5,50 Setting for Torque in Nm
- > multil,1,5,2 Setting for Mechanical Power in nW
- > multil? Setting to read back and display data

Example script to return results for Mechanical Power, Torque & Speed (in rpm):

```
>
>
> multil,0
> multil,1,5,2
> multil,2,5,50
> multil,3,5,60
> multil?
-1.8846E-7,-2.0984E-3,8.5765E-4
```

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